

The World of Modulation Spaces

Nowadays there we dispose over a rich variety of *Banach spaces of functions*, which for me in the spirit of Hans Triebel but also in the Russian tradition means: Banach space of smooth functions of (tempered) distributions.

The literature knows (rearrangement invariant) Banach function spaces: Here the membership of a function depends only on the level sets, i.e. on the measure of the sets $\{x \mid |f(x)| \geq \alpha\}$, as a function of $\alpha > 0$.

The membership of f in some Sobolev, or Besov-, or Triebel-Lizorkin spaces describes the smoothness, typically using a modulus of continuity, or *dyadic partitions of unity* (based on Paley-Littlewood Theory).



Comparing $\mathcal{S}(\mathbb{R}^d)$ with $\mathcal{S}_0(\mathbb{R}^d)$

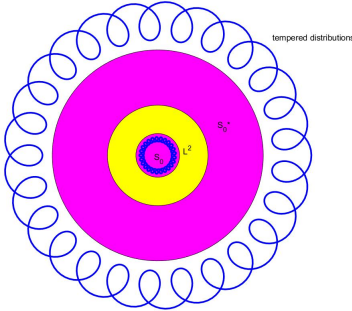


Figure: The Banach Gelfand Triple surrounded by the Schwartz space (inside) and the space of tempered distributions, containing everything.



All the spaces, including Wiener amalgams

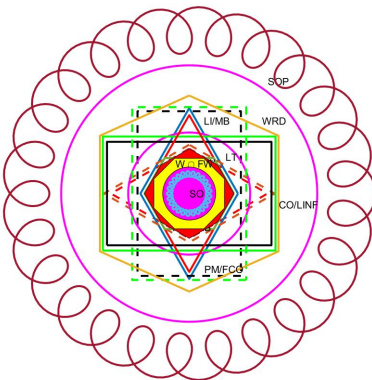


Figure: schwwienall1.jpg



What do we need for “generalized functions”

First of all we need a reservoir of “nice/ordinary” functions, usually called a space of test functions. Then we can proceed to look at the dual space which may include already some interesting objects which cannot be treated as ordinary functions.

If we start with the Banach algebra $(\mathbf{C}_0(\mathbb{R}^d), \|\cdot\|_\infty)$ we can identify (or call by definition) the dual spaces the space $(\mathbf{M}_b(\mathbb{R}^d), \|\cdot\|_{\mathbf{M}_b})$ (of bounded measures (regular Borel measures)). But then $\mathbf{C}_0(\mathbb{R}^d)$ is not embedded into $\mathbf{M}_b(\mathbb{R}^d)$ in a natural way. If we make the space smaller, e.g. $L^1 \cap \mathbf{C}_0(\mathbb{R}^d)$ (with the natural norm) we have already such an embedding, but *Wiener’s Algebra* is much better. It is obtained by decomposing $f \in \mathbf{C}_0(\mathbb{R}^d)$ into localized blocks and requiring absolute convergence.

Taking the Fourier transform of these local pieces and requiring membership of this TF-decomposition can already be used as a possible definition of $(\mathbf{S}_0(\mathbb{R}^d), \|\cdot\|_{\mathbf{S}_0})$.

An equivalent norm is in fact:

More elaborate choices

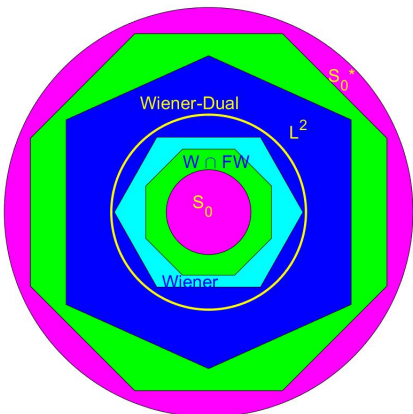


Figure: WienSOSOP2.jpg



New and Classical Spaces

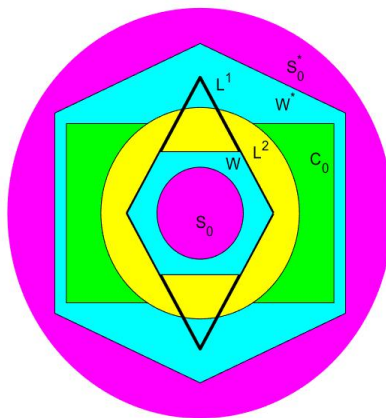
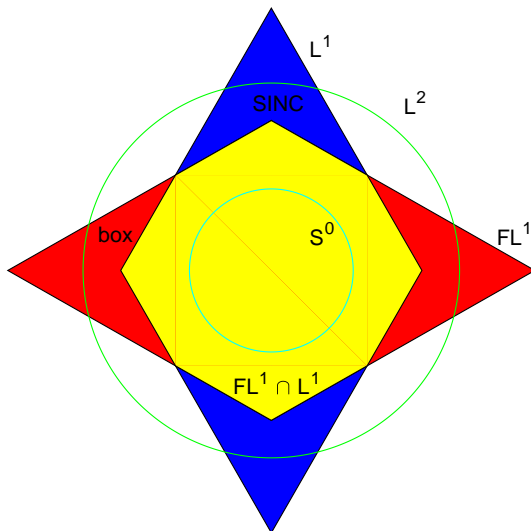


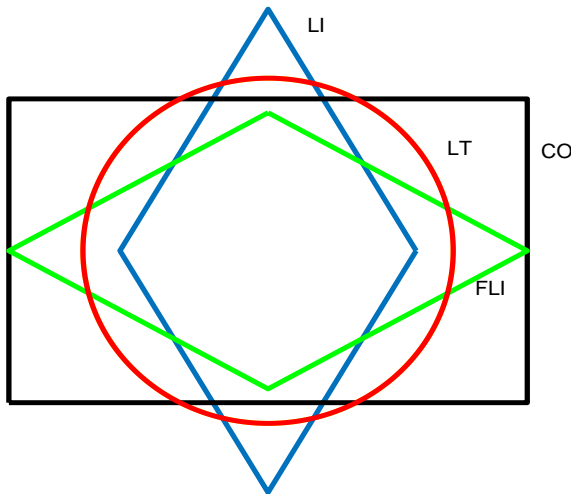
Figure: LILTSOBWien.jpg



A closeup on the known spaces

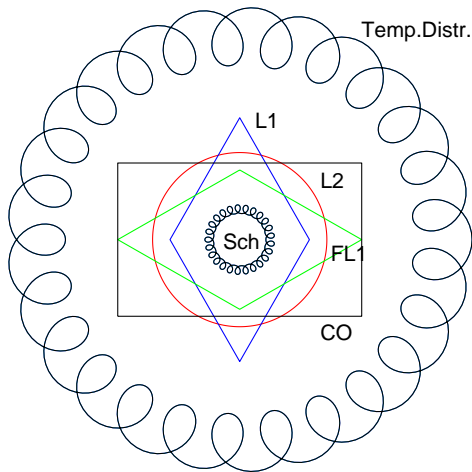


A schematic description of the situation: L^1, L^2



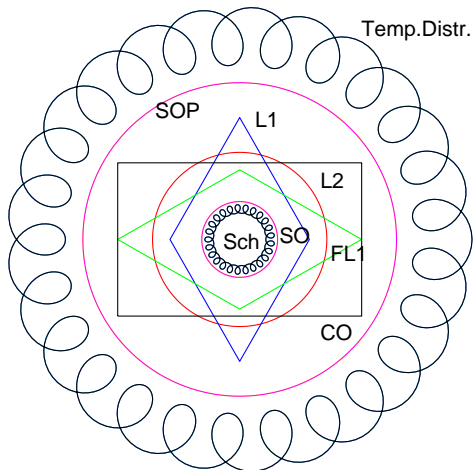
A schematic description of the situation: L^1, L^2, C_0

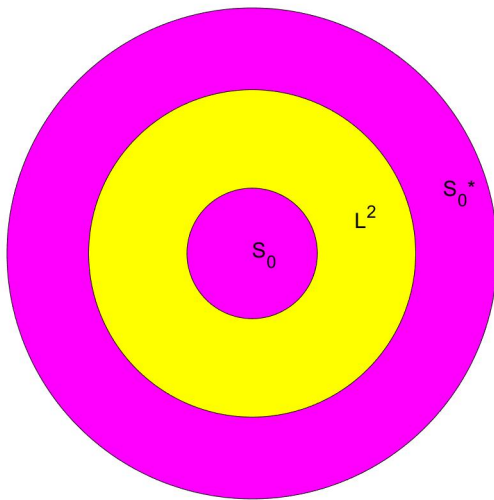
Universe of tempered distributions



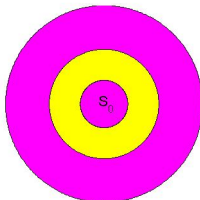
A schematic description that we are going for

Universe including SO and SOP

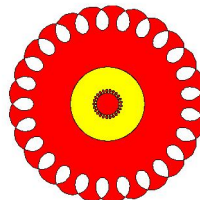
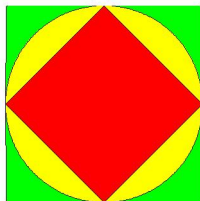




Fei-BGTr



Schwartz GTr

 l^1, l^2, l^∞ 

Sobolev GTr

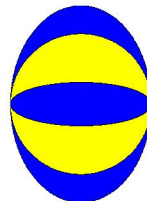


Figure: BanGelfTrip1.jpg: different Gelfand Triples: The S_0 -triple, l^1, l^2, l^∞

BANACH GELFAND TRIPLES: a new category

Definition

A triple, consisting of a Banach space B , which is dense in some Hilbert space \mathcal{H} , which in turn is contained in B' is called a **Banach Gelfand triple**.

Definition

If $(B_1, \mathcal{H}_1, B'_1)$ and $(B_2, \mathcal{H}_2, B'_2)$ are Gelfand triples then a linear operator T is called a **[unitary] Gelfand triple isomorphism** if

- ① A is an isomorphism between B_1 and B_2 .
- ② A is **[a unitary operator resp.]** an isomorphism between \mathcal{H}_1 and \mathcal{H}_2 .
- ③ A extends to norm-to-norm continuous isomorphism between B'_1 and B'_2 **which is then IN ADDITION w^* - w^* -continuous!**

A pictorial presentation

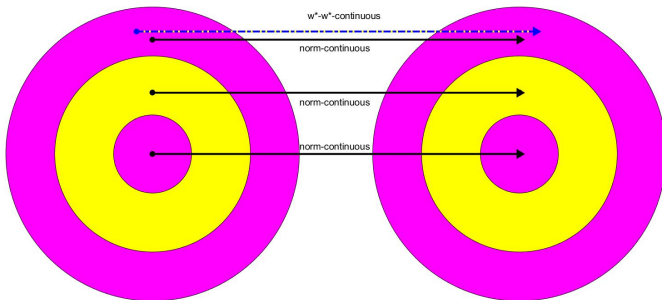


Figure: The description of a Banach space morphism.

Banach Gelfand Triples, the prototype

In principle every CONB (= *complete orthonormal basis*) $\Psi = (\psi_i)_{i \in I}$ for a given Hilbert space \mathcal{H} can be used to establish such a unitary isomorphism, by choosing as \mathbf{B} the space of elements within \mathcal{H} which have an absolutely convergent expansion, i.e. satisfy $\sum_{i \in I} |\langle x, \psi_i \rangle| < \infty$.

For the case of the Fourier system as CONB for $\mathcal{H} = \mathbf{L}^2([0, 1])$, i.e. the corresponding definition is already around since the times of N. Wiener: $\mathbf{A}(\mathbb{T})$, the space of absolutely continuous Fourier series. It is also not surprising in retrospect to see that the dual space $\mathbf{PM}(\mathbb{T}) = \mathbf{A}(\mathbb{T})'$ is space of *pseudo-measures*. One can extend the classical Fourier transform to this space, and in fact interpret this extended mapping, in conjunction with the classical Plancherel theorem as the first unitary Banach Gelfand triple isomorphism, between $(\mathbf{A}, \mathbf{L}^2, \mathbf{PM})(\mathbb{T})$ and $(\ell^1, \ell^2, \ell^\infty)(\mathbb{Z})$.



The Segal Algebra $(\mathcal{S}_0(\mathbb{R}^d), \|\cdot\|_{\mathcal{S}_0})$, 1979

In the last 2-3 decades the Segal algebra $(\mathcal{S}_0(\mathbb{R}^d), \|\cdot\|_{\mathcal{S}_0})$ (equal to the modulation space $(M^1(\mathbb{R}^d), \|\cdot\|_{M^1})$) and its dual, $(\mathcal{S}'_0(\mathbb{R}^d), \|\cdot\|_{\mathcal{S}'_0})$ have gained importance for many questions of Gabor analysis or time-frequency analysis in general.

It can be characterized as the **smallest (non-trivial) Banach space of (continuous and integrable) functions with the property**, that time-frequency shifts acts isometrically on its elements, i.e. with

$$\|T_x f\|_{\mathcal{B}} = \|f\|_{\mathcal{B}}, \quad \text{and} \quad \|M_s f\|_{\mathcal{B}} = \|f\|_{\mathcal{B}}, \quad \forall f \in \mathcal{B},$$

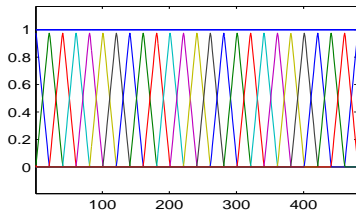
where T_x is the usual translation operator, and M_s is the *frequency shift* operator, i.e. $M_s f(t) = e^{2\pi i s \cdot t} f(t)$, $t \in \mathbb{R}^d$.

This description implies that $\mathcal{S}_0(\mathbb{R}^d)$ is also **Fourier invariant!**

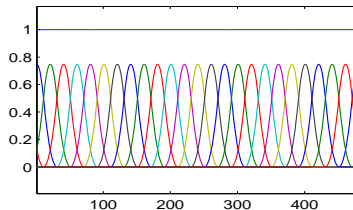


Illustration of the B-splines providing BUPUs

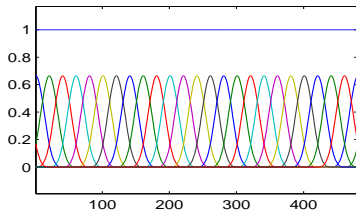
spline of degree 1



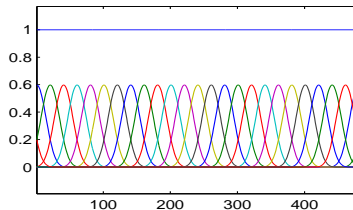
spline of degree 2



spline of degree 3



spline of degree 4



The Segal Algebra $(\mathbf{S}_0(\mathbb{R}^d), \|\cdot\|_{\mathbf{S}_0})$: description

There are many different ways to describe $(\mathbf{S}_0(\mathbb{R}^d), \|\cdot\|_{\mathbf{S}_0})$. Originally it has been introduced as *Wiener amalgam space* $\mathbf{W}(\mathcal{FL}^1, \ell^1)(\mathbb{R}^d)$, but the standard approach is to describe it via the STFT (short-time Fourier transform) using a Gaussian window given by $g_0(t) = e^{-\pi|t|^2}$.

A short description of the Wiener Amalgam space for $d = 1$ is as follows: Starting from the basis of B-splines of order ≥ 2 (e.g. triangular functions or cubic B-splines), which form a (smooth and uniform) partition of the form $(\varphi_n) := (T_n\varphi)_{n \in \mathbb{Z}}$ we can say that $f \in \mathcal{FL}^1(\mathbb{R}^d)$ belongs to $\mathbf{W}(\mathcal{FL}^1, \ell^1)(\mathbb{R}^d)$ if and only if

$$\|f\| := \sum_{n \in \mathbb{Z}} \|\widehat{f \cdot \varphi_n}\|_{L^1} < \infty.$$

Using tensor products the definition extends to $d \geq 2$.



Banach Gelfand Triple $(\mathbf{S}_0, L^2, \mathbf{S}'_0)$: BASICS

Let us collect a few facts concerning this Banach Gelfand Triple (BGTr), based on the Segal algebra $(\mathbf{S}_0(\mathbb{R}^d), \|\cdot\|_{\mathbf{S}_0})$:

- $\mathbf{S}_0(\mathbb{R}^d)$ is dense in $(L^2(\mathbb{R}^d), \|\cdot\|_2)$, in fact within any $(L^p(\mathbb{R}^d), \|\cdot\|_p)$, with $1 \leq p < \infty$ (or in $(\mathbf{C}_0(\mathbb{R}^d), \|\cdot\|_\infty)$);
- Any of the L^p -spaces, with $1 \leq p \leq \infty$ is continuously embedded into $\mathbf{S}'_0(\mathbb{R}^d)$;
- Any translation bounded measure belongs to $\mathbf{S}'_0(\mathbb{R}^d)$, in particular any Dirac-comb $\bigsqcup_\Lambda := \sum_{\lambda \in \Lambda} \delta_\lambda$, for $\Lambda \triangleleft \mathbb{R}^d$.
- $\mathbf{S}_0(\mathbb{R}^d)$ is w^* -dense in $\mathbf{S}'_0(\mathbb{R}^d)$, i.e. for any $\sigma \in \mathbf{S}'_0(\mathbb{R}^d)$ there exists a sequence of test functions s_n in $\mathbf{S}_0(\mathbb{R}^d)$ such that

$$(1) \quad \int_{\mathbb{R}^d} f(x) s_n(x) dx \rightarrow \sigma(f), \quad \forall f \in \mathbf{S}_0(\mathbb{R}^d).$$



The key-players for time-frequency analysis

Time-shifts and Frequency shifts

$$T_x f(t) = f(t - x)$$

and $x, \omega, t \in \mathbb{R}^d$

$$M_\omega f(t) = e^{2\pi i \omega \cdot t} f(t).$$

Behavior under Fourier transform

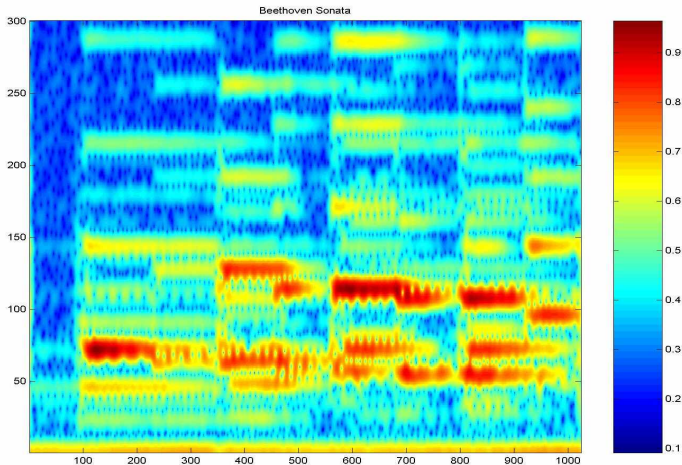
$$(T_x f)^\wedge = M_{-x} \hat{f} \quad (M_\omega f)^\wedge = T_\omega \hat{f}$$

The Short-Time Fourier Transform

$$V_g f(\lambda) = \langle f, M_\omega T_t g \rangle = \langle f, \pi(\lambda) g \rangle = \langle f, g_\lambda \rangle, \quad \lambda = (t, \omega);$$



A Typical Musical STFT



Spectrogram versus Gabor Analysis

Assuming that we use as a “window” a Schwartz function $g \in \mathcal{S}(\mathbb{R}^d)$, or even the Gauss function $g_0(t) = \exp(-\pi|t|^2)$, we can define the spectrogram for general tempered distributions $f \in \mathcal{S}'(\mathbb{R}^d)$! It is a continuous function over *phase space*.

In fact, for the case of the Gauss function it is *analytic* and in fact a member of the *Fock space*, of interest within complex analysis.

Both from a practical point of view and in view of this good smoothness one may expect that it is enough to *sample this spectrogram*, denoted by $V_g(f)$ and still be able to reconstruct f (in analogy to the reconstruction of a band-limited signal from regular samples, according to Shannon's theorem).



The continuous reconstruction formula

Now we can apply a simple abstract principle: Given an isometric embedding T of \mathcal{H}_1 into \mathcal{H}_2 the inverse (in the range) is given by the adjoint operator $T^* : \mathcal{H}_2 \rightarrow \mathcal{H}_1$, simply because

$$\langle h, h \rangle_{\mathcal{H}_1} = \|h\|_{\mathcal{H}_1}^2 = (!) \|Th\|_{\mathcal{H}_2}^2 = \langle Th, Th \rangle_{\mathcal{H}_2} = \langle h, T^*Th \rangle_{\mathcal{H}_1}, \quad \forall h \in \mathcal{H}_1,$$

and thus by the *polarization principle* $T^*T = Id$

In our setting we have (assuming $\|g\|_2 = 1$) $\mathcal{H}_1 = L^2(\mathbb{R}^d)$ and $\mathcal{H}_2 = L^2(\mathbb{R}^d \times \widehat{\mathbb{R}}^d)$, and $T = V_g$. It is easy to check that

$$V_g^*(F) = \int_{\mathbb{R}^d \times \widehat{\mathbb{R}}^d} F(\lambda) \pi(\lambda) g \, d\lambda, \quad F \in L^2(\mathbb{R}^d \times \widehat{\mathbb{R}}^d), \quad (7)$$

understood in the weak sense, i.e. for $h \in L^2(\mathbb{R}^d)$ we expect:

$$\langle V_g^*(F), h \rangle_{L^2(\mathbb{R}^d)} = \int_{\mathbb{R}^d \times \widehat{\mathbb{R}}^d} F(x) \cdot \langle \pi(\lambda) g, h \rangle_{L^2(\mathbb{R}^d)} d\lambda. \quad (8)$$



Continuous reconstruction formula II

Putting things together we have

$$\langle f, h \rangle = \langle V_g^*(V_g(f)), h \rangle = \int_{\mathbb{R}^d \times \widehat{\mathbb{R}}^d} V_g(f)(\lambda) \cdot \overline{V_g(h)(\lambda)} d\lambda. \quad (9)$$

A more suggestive presentation uses the symbol $g_\lambda := \pi(\lambda)g$ and describes the inversion formula for $\|g\|_2 = 1$ as:

$$f = \int_{\mathbb{R}^d \times \widehat{\mathbb{R}}^d} \langle f, g_\lambda \rangle g_\lambda d\lambda, \quad f \in L^2(\mathbb{R}^d). \quad (10)$$

This is quite analogous to the situation of the Fourier transform

$$(6) \quad f = \int_{\mathbb{R}^d} \langle f, \chi_s \rangle \chi_s ds, = \int_{\mathbb{R}^d} \hat{f}(x) e^{2\pi i s \cdot} ds \quad f \in L^2(\mathbb{R}^d), \quad (11)$$

with $\chi_s(t) = \exp(2\pi i \langle s, t \rangle)$, $t, s \in \mathbb{R}^d$, describing the “pure frequencies” (plane waves, resp. *characters* of \mathbb{R}^d).



Introducing the space $(\mathbf{S}_0(\mathbb{R}^d), \|\cdot\|_{\mathbf{S}_0})$

The Banach space (and actually Segal algebra) $(\mathbf{S}_0(\mathbb{R}^d), \|\cdot\|_{\mathbf{S}_0})$ has been introduced by the speaker in 1979, in a paper in Monatshefte f. Math., entitled “On a New Segal Algebra”. Most of the basic properties of this space of test functions, including minimality among Banach spaces of functions which are isometrically invariant under time-frequency shifts, and the Fourier invariance have been demonstrated already in that first paper. Modern approaches to this space, called $(M^1(\mathbb{R}^d), \|\cdot\|_{M^1})$ in the book of Gröchenig, can be found in his book. It is now common practice to define $(\mathbf{S}_0(\mathbb{R}^d), \|\cdot\|_{\mathbf{S}_0})$ via the membership of the STFT (short time Fourier transform) with respect to a Gaussian window $g_0(t) = e^{-\pi|t|^2}$ and choose as a norm

$$\|f\|_{\mathbf{S}_0} := \int_{\mathbb{R}^{2d}} |V_g(\lambda)| d\lambda = \|V_g(f)\|_1.$$

(12)



Characterization of $\mathcal{S}'_0(\mathbb{R}^d)$ and w^* -convergence

A tempered distribution $\sigma \in \mathcal{S}'(\mathbb{R}^d)$ belongs to $\mathcal{S}'_0(\mathbb{R}^d)$ if and only if its (continuous) STFT is a *bounded* function. Furthermore convergence corresponds to uniform convergence of the spectrogram (different windows give equivalent norms!).

We can also extend the **Fourier transform** from $\mathcal{S}_0(\mathbb{R}^d)$ to $\mathcal{S}'_0(\mathbb{R}^d)$ via the usual formula $\hat{\sigma}(f) := \sigma(\hat{f})$.

The weaker convergence, arising from the functional analytic concept of **w^* -convergence** has the following very natural characterization: A (bounded) sequence σ_n is w^* -convergence to σ_0 if and only if for one (resp. every) $\mathcal{S}_0(\mathbb{R}^d)$ -window g one has

$$V_g(\sigma_n)(\lambda) \rightarrow V_g(\sigma_0)(\lambda) \quad \text{for } n \rightarrow \infty,$$

uniformly over compact subsets of phase-space.



Applications to Translation Invariant Systems

Engineers like to describe “translation invariant systems” as convolution operators by some *impulse response*, or equivalently by the pointwise multiplication of \hat{f} (the input signal) by some *transfer function*. In sloppy terms:

$$T(f) = \mu * f, \quad \text{with} \quad \mu = T(\delta_0)$$

$$\widehat{Tf} = h \cdot \hat{f}.$$

Here we refer to the engineering terminology: A TILS is linear operator (often the domain is left undefined!) with the property that

$$T_x \circ T = T \circ T_x, \quad x \in \mathbb{R}^d.$$



Translation Invariant Systems II, TILS2

Theorem

$$\mathcal{H}_G(\mathbf{S}_0(\mathbb{R}^d), \mathbf{S}'_0(\mathbb{R}^d)) = \mathbf{S}'_0(\mathbb{R}^d)$$

i.e. for every $T \in \mathcal{L}(\mathbf{S}_0, \mathbf{S}'_0)$ commuting with translation there is a unique $\sigma = \sigma_T$ such that $Tf(x) = \sigma(T_x f^\vee)$ where $f^\vee(x) = f(-x)$. Also the converse is true, and the operator norm of T is equivalent to the \mathbf{S}'_0 -norm of σ .

Corollary

Any translation invariant operator from $(L^p(\mathbb{R}^d), \|\cdot\|_p)$ to $(L^q(\mathbb{R}^d), \|\cdot\|_q)$, $1 \leq p, q < \infty$ can be represented (on $\mathbf{S}_0(\mathbb{R}^d)$) as a convolution operator by $\sigma \in \mathbf{S}'_0(\mathbb{R}^d)$ or with the transfer “function” $h = \hat{\sigma}$ (Fourier multipliers).

Classical Analysis and Summability

Among the functions typically used in Fourier analysis only the so-called BOX-function ($\mathbf{1}_Q$) (being discontinuous) and its Fourier transform, the SINC-function (not belonging to $L^1(\mathbb{R}^d)$) are NOT elements of $\mathbf{S}_0(\mathbb{R})$, while (according to F. Weisz)

all the classical summability kernels belong to $\mathbf{S}_0(\mathbb{R}^d)$

.

The space $\mathbf{S}_0(\mathbb{R}^d)$ is also the natural domain for the *Poisson summation formula*, another important tool in Fourier analysis:

$$\sum_{k \in \mathbb{Z}^d} f(k) = \sum_{n \in \mathbb{Z}^d} \hat{f}(n), \quad \forall f \in \mathbf{S}_0(\mathbb{R}^d). \quad (13)$$

There are counter-examples, but they all work only when one is using function spaces not contained in $\mathbf{S}_0(\mathbb{R}^d)$.



A First Application to the Fourier Transform

When it comes to the approximate realization of a Fourier related task we can point to joint work with N. Kaiblinger:

Theorem

Given $f \in \mathbf{S}_0(\mathbb{R})$ and $\varepsilon > 0$ it is enough to apply the FFT to a sequence of equi-distant samples, taken sufficiently fine and over a sufficiently long interval, then apply the FFT to this sequence and regain a continuous (and compactly supported) function \hat{f}_a in $\mathbf{S}_0(\mathbb{R})$ via (linear or) quasi-inteprolation, with

$$\|\hat{f} - \hat{f}_a\|_{\mathbf{S}_0} < \varepsilon.$$



The Role of $\mathbf{S}_0(\mathbb{R}^d)$ for Gabor Analysis III

This can be used to check that the representation formula (14) is also valid in the $(\mathbf{S}_0(\mathbb{R}^d), \|\cdot\|_{\mathbf{S}_0})$ -sense for $f \in \mathbf{S}_0(\mathbb{R}^d)$ and can be extended (now with w^* -convergence) to general $f \in \mathbf{S}'_0(\mathbb{R}^d)$.

For $g \in \mathbf{S}_0(\mathbb{R}^d)$ it is true that a small **jitter error**, i.e. using instead of $V_g(\lambda) = \langle f, g_\lambda \rangle$ some nearby sampling value $V_g(\lambda + \gamma_\lambda)$ with $|\gamma_\lambda| \leq \gamma_0$ for some small constant γ_0 . Then, e.g., the reconstruction of $f \in \mathbf{S}_0(\mathbb{R}^d)$ from these slightly perturbed samples will show error (in the \mathbf{S}_0 -norm sense!).

Also for the computation of *approximate dual Gabor windows* h it is important to ensure a small error in the \mathbf{S}_0 -norm sense, because otherwise it is *not possible* to control the error of the computable operator $\sum_{\lambda \in \Lambda} \langle f, g_\lambda \rangle h_\lambda$ in the operator norm sense (even on $(L^2(\mathbb{R}^d), \|\cdot\|_2)$).



The Role of $\mathbf{S}_0(\mathbb{R}^d)$ for Gabor Analysis VI

In the continuous setting and for Gabor frames with $\mathbf{S}_0(\mathbb{R}^d)$ -atoms g we have the following situation:

Theorem

Given a Gabor frame (g, Λ) with $g \in \mathbf{S}_0(\mathbb{R}^d)$ one has:

- the coefficient mapping $\mathbf{C} : f \rightarrow V_g(f)|_\Lambda$ is an BGTr homomorphism from $(\mathbf{S}_0, L^2, \mathbf{S}'_0)(\mathbb{R}^d)$ into $(\ell^1, \ell^2, \ell^\infty)(\Lambda)$.
- For $\tilde{g} = S^{-1}(g) \in \mathbf{S}_0(\mathbb{R}^d)$ the Gabor synthesis mapping

$$\mathbf{R} : (\mathbf{c}_\lambda) \rightarrow \sum_{\lambda \in \Lambda} \mathbf{c}_\lambda \tilde{g}_\lambda$$

is a BGTr homomorphism $(\ell^1, \ell^2, \ell^\infty)(\Lambda) \rightarrow (\mathbf{S}_0, L^2, \mathbf{S}'_0)(\mathbb{R}^d)$;

- \mathbf{R} is a left inverse to \mathbf{C} : $\mathbf{R} \circ \mathbf{C} = \text{Id}$ on $(\mathbf{S}_0, L^2, \mathbf{S}'_0)$.

The Kernel Theorem

It is clear that such operators between functions on \mathbb{R}^d cannot all be represented by integral kernels using locally integrable $K(x, y)$ in the form

$$Tf(x) = \int_{\mathbb{R}^d} K(x, y)f(y)dy, \quad x, y \in \mathbb{R}^d, \quad (15)$$

because clearly multiplication operators should have their support on the main diagonal, but $\{(x, x) \mid x \in \mathbb{R}^d\}$ is just a set of measure zero in $\mathbb{R}^d \times \mathbb{R}^d$!

Also the expected “rule” to find the kernel, namely

$$K(x, y) = T(\delta_y)(x) = \delta_x(T(\delta_y)) \quad (16)$$

might not be meaningful at all.



The Schwartz Kernel Theorem

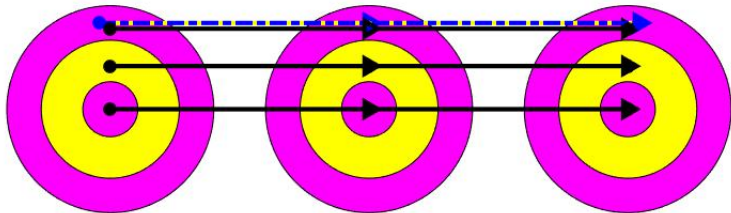
The other well known version of the kernel theorem makes use of the *nuclearity* of the *Frechet space* $\mathcal{S}(\mathbb{R}^d)$ (so to say the complicated topological properties of the system of seminorms defining the topology on $\mathcal{S}(\mathbb{R}^d)$).

Note that the description cannot be given anymore in the form (15) but has to be replaced by a “weak description”. This is part of the following well-known result due to L. Schwartz.

Theorem

There is a natural isomorphism between the vector space of all linear operators from $\mathcal{S}(\mathbb{R}^d)$ into $\mathcal{S}'(\mathbb{R}^d)$, i.e. $\mathcal{L}(\mathcal{S}, \mathcal{S}')$, and the elements of $\mathcal{S}'(\mathbb{R}^{2d})$, via $\langle Tf, g \rangle = \langle K, f \otimes g \rangle$, for $f, g \in \mathcal{S}(\mathbb{R}^d)$.





Applications to Gabor Multipliers

This last property can be used to e.g. describe the best approximation of a given operator by a Gabor multiplier. The most important Gabor multipliers arise from tight regular Gabor frames, i.e. families of the form $(\pi(\lambda)g)_{\lambda \in \Lambda}$, with Λ being any lattice in $\mathbb{R}^d \times \widehat{\mathbb{R}}^d$, with the property (writing g_λ for $\pi(\lambda)g$) with the following reconstruction property:

$$f = \sum_{\lambda \in \Lambda} \langle f, g_\lambda \rangle g_\lambda, \quad f \in (\mathbf{S}_0, \mathbf{L}^2, \mathbf{S}'_0). \quad (17)$$

We also can write $P_\lambda : f \rightarrow \langle f, g_\lambda \rangle g_\lambda$. Given a numerical sequence over the lattice (m_λ) the Gabor multiplier $G_m := \sum_{\lambda \in \Lambda} m(\lambda)P_\lambda$. The problem of best approximation of some \mathcal{HS} operator by Gabor multipliers can be reformulated as an approximation problem using spline-type spaces via the Kohn-Nirenberg connection.



Approximation by discrete and periodic signals

The combination of two such operators, just with the assumption that the sampling lattice Λ_1 is a subgroup (of finite index N) of the periodization lattice Λ_2 implies that

$$\bigsqcup_{\Lambda_2} * [\bigsqcup_{\Lambda_1} \cdot f] = \bigsqcup_{\Lambda_1} \cdot [\bigsqcup_{\Lambda_2} * f], \quad f \in \mathbf{S}_0(\mathbb{R}^d). \quad (21)$$

For illustration let us take $d = 1$ and $\Lambda_1 = \alpha\mathbb{Z}$, $\Lambda_2 = N\alpha\mathbb{Z}$ and hence $\Lambda_1^\perp = (1/\alpha)\mathbb{Z}$. Then the periodic and sampled signal arising from equ. 21 corresponds to a vector $\mathbf{a} \in \mathbb{C}^N$ and the distributional Fourier transform of the periodic, discrete signal is completely characterized is again discrete and periodic and its generating sequence $\mathbf{b} \in \mathbb{C}^N$ can be obtained via the DFT (FT of quotient group), e.g. $N = k^2$, $\alpha = 1/k$, and period k .



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