

# Computational Aspects of Time-Frequency and Gabor Analysis

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**[www.nuhag.eu](http://www.nuhag.eu)**

39th Meeting of Prague computer science seminar



# Spectrogram of a Piece of ASONANCE

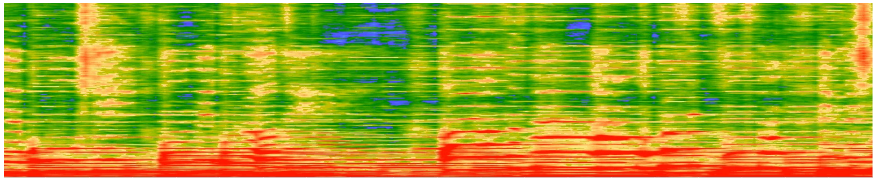


Figure: Asonance02.jpg:

Spectrogram based on a YOUTUBE recording of ASONANCE

horizontal axis: time, vertical axis: frequency



## TEST



This is another piece of music of ASONANCE which can be viewed at YOUTUBE.



# ChromatOrg1

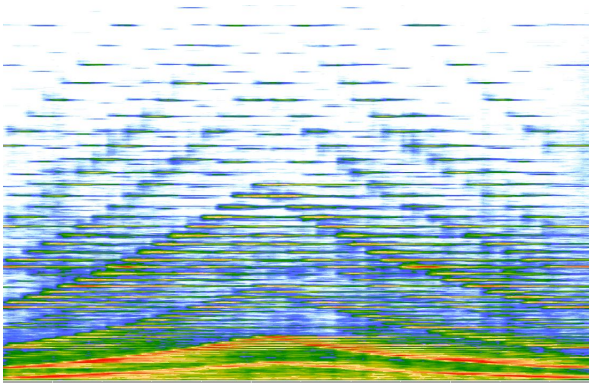


Figure: ChromatOrg1.jpg









# Structure of the talk

**Fourier Analysis** started in 1822 with a publication of **J.B.Fourier**, presenting a solution of the *heat equation*. A solid foundation of this *integral transform*, based on the Lebesgue integral (using  $(L^1(\mathbb{R}^d), \|\cdot\|_1)$  and  $(L^2(\mathbb{R}^d), \|\cdot\|_2)$ ). In 1965 the FFT, the so-called Fast Fourier Transform (i.e. an efficient implementation of the DFT, the discrete Fourier transform) was suggested.

- 1 Examples and Demonstrations
- 2 Background on Fourier Transforms
- 3 Short Time FT and Gabor Analysis
- 4 Algorithmic Questions
- 5 Applications and Challenges



# Jarník Lecture in Prag, 2017

In my **Jarnik Lecture** in Prag, October 4th, 2017, I have presented the following aspects of Fourier Analysis:

- 1 History of Fourier Analysis
- 2 From Complex Numbers to Digital Signal Processing
- 3 Mathematical Developments, up to Distribution Theory
- 4 Real World Applications

In the current semester (also sommer 2017 and 2018) I have been teaching a pair of courses, one starting from Linear Algebra, using MATLAB, the other presenting a simplified theory of *mild distributions*, see [www.nuhag.eu/prag18](http://www.nuhag.eu/prag18).



Hans G. Feichtinger: Jarník Lecture: Fourier Analysis in the 21st Century. Talk at Charles University. Oct. 4th, 2017, see [www.nuhag.eu/talks](http://www.nuhag.eu/talks), search Feichtinger.



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- 1 Digital Signal and Image Processing
- 2 Mobile Communication
- 3 CD-player, HiFi standard:  $44100 = (2 \cdot 3 \cdot 5 \cdot 7)^2$  s/sec;
- 4 MP3 Audio Compression
- 5 JPEG Image Compression
- 6 Tomography
- 7 Modern Solvers for PDE
- 8 Spectroscopy, Crystallography
- 9 Discovery of Gravitational Waves



# Different Flavours of the Fourier Transform

Most books on the Fourier Transform, including those for engineers or physicists, distinguish between different types of signals:

- continuous variable, periodic functions (Fourier series);
- continuous variables, non-periodic (Fourier transform);
- discrete variables, non-periodic (time series);
- discrete and periodic signals (DFT, FFT);

Abstract Harmonic Analysis views them as versions of *one principle*, providing a *decomposition of functions* over locally compact Abelian groups, such as  $\mathbb{U}, \mathbb{R}^n, \mathbb{Z}^k, \mathbb{Z}_N$ , into “basic building blocks”, called *pure frequencies* or *plane waves*.



Gianfranco Cariolaro Unified Signal Theory, Springer, London, (2011) p.xx+927.



Jens Fischer: Four Particular Cases of the Fourier Transform Mathematics (MDPI), Vol.12 No.6, (2018), p.335.



# The Classical Integral Formula

$$\hat{f}(s) = \int_{\mathbb{R}^d} f(t) \cdot e^{-2\pi i s \cdot t} dt, \quad t, s \in \mathbb{R}^d, \quad (1)$$

where  $s \cdot t$  denotes the *scalar product* of  $s, t \in \mathbb{R}^d$ .

The *inverse Fourier transform* then has the form

$$f(t) = \int_{\mathbb{R}^d} \hat{f}(\omega) \cdot e^{2\pi i t \cdot \omega} d\omega, \quad (2)$$

Strictly speaking this inversion formula only makes sense under the additional hypothesis that  $\hat{f} \in \mathbf{L}^1(\mathbb{R}^d)$ , which is *not* satisfied for arbitrary functions  $f \in \mathbf{L}^1(\mathbb{R}^d)$ . In the general case ( $f \in \mathbf{L}^1(\mathbb{R}^d)$ ) one can obtain  $f$  from  $\hat{f}$  using classical summability methods, convergent in the  $\mathbf{L}^1$ -norm.



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Downloaded from <http://ajph.org/> on November 10, 2014



# Convolution powers, starting from random vector

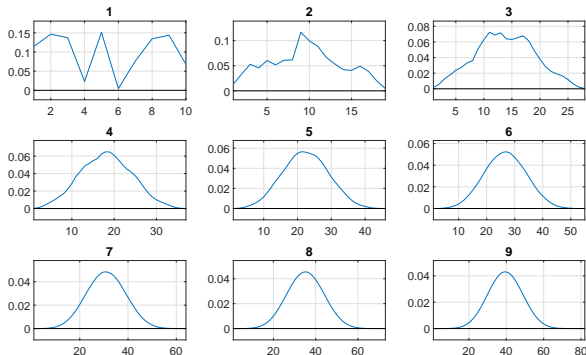


Figure: convpowers02.eps

Experimental evidence for the **central limit theorem**



# The DFT: Discrete Fourier Transform

Instead of describing it through formulas, let us describe it by a simple reinterpretation, and by what one can say about it:

- 1 The DFT can be described as the linear mapping which starts from a sequence of coefficients, defining a polynomial

$$p_{\mathbf{a}}(x) := a_1 + a_2x + \cdots a_nx^{n-1},$$

which is then evaluated at the unit roots of order  $N$ , starting at  $1 = \omega^0$ , in the clockwise sense.

Hence the *matrix realizing the DFT* is just a Vandermonde-matrix, properly arranged (and thus invertible!).

- 2 This explains immediately the so-called **Convolution Theorem**: The *Cauchy-Product* providing the coefficients of a product polynomial is the same as the coefficients of the polynomial obtained by multiplying their values at unit roots properly!).



- ① But looking at the entries of the Fourier matrix one easily can verify that they are orthogonal vectors, thus (up to the scaling factor  $\sqrt{N}$ ) the Fourier transform is a *unitary mapping*. Consequently it is just a change of basis to another orthonormal basis, consisting of *pure frequencies*.
- ② Also it is easy to understand that regular sampling (leaving only e.g. every second or third sample value, if 2 or 3 divide  $N$ ) corresponds to periodization on the Fourier transform side. This is the basis for the understanding of the **Shannon Sampling Theorem** which allows to recover *band-limited signals* from (dense and regular) sampling sequence (which is in turn the basis for digital audio, using just 44100 samples per second)!



## uroots12num.pdf

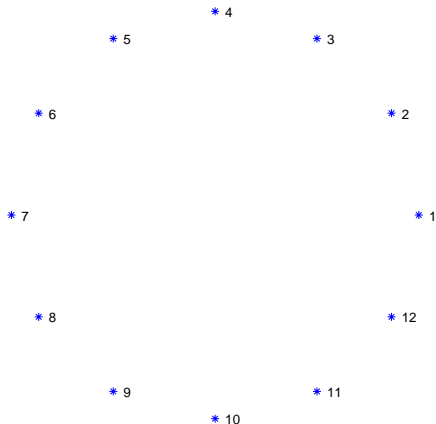


Figure: uroots12num.pdf



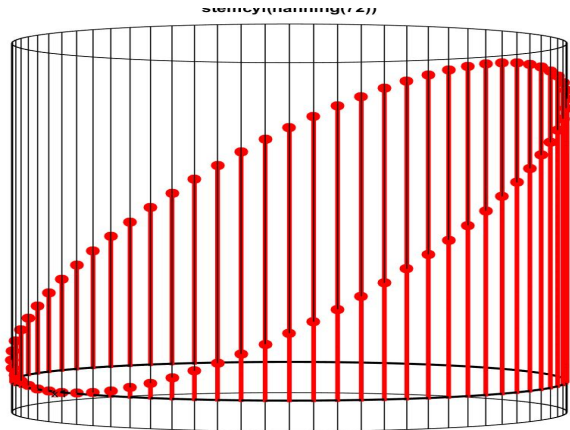


Figure: stemcyl72.jpg



## shannon14415.pdf

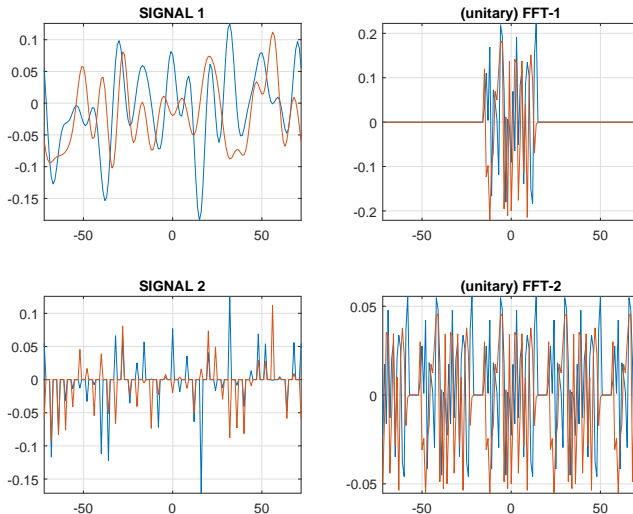


Figure: shannon14415.pdf



# Image Processing and FFT2

Convolution and the Fourier transform are crucial in order to characterize *time-invariant linear systems* as convolution operators (convolution by a so-called *impulse response*) or as a multiplication operator (by the so-called *transfer function*, which is simply the Fourier transform of the impulse response).

Similar facts are valid in higher dimensions. For  $d = 2$ , i.e. for applications in image processing we have operators which commute with ordinary  $2d$ -translation, such as a blurring operator or an edge-detection operator.

The (invariant) functions, i.e. joint (complex-valued) eigenvectors of all these translation operators turn out to be the *plane waves*, or the (tensor) products of pure frequencies. This separation argument allows to implement the FFT2 by iteration of ordinary FFTs (row-wise/column-wise). Impulse responses are now called *point-spread functions*.



# Some MATLAB Code

```
>> n = 512; PIC = rand(n); x = rand(n,1);
F = fft(eye(n));
norm(F*x - fft(x)),
ans = 1.9386e-13
>> norm(F-F.', 'fro') (showing real symmetry)
ans = 6.3377e-14
norm(F*PIC*F - fft2(PIC), 'fro')
ans = 1.1192e-10
```

This experiments also indicates why the order (FFT row-wise or column-wise) does not matter! (associativity law)



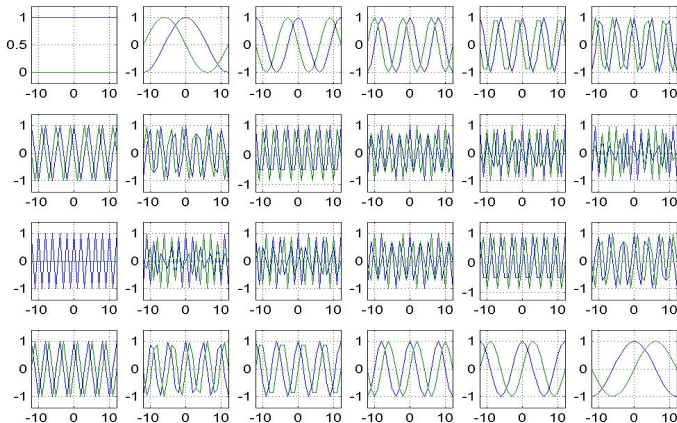
Hans G. Feichtinger: presentation at MATLAB Expo, Munich, 2016  
[http://univie.ac.at/nuhag-php/dateien/talks/3609\\_EXP0FeiE6.pdf](http://univie.ac.at/nuhag-php/dateien/talks/3609_EXP0FeiE6.pdf)



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# The rows of the Fourier matrix (real/imag)



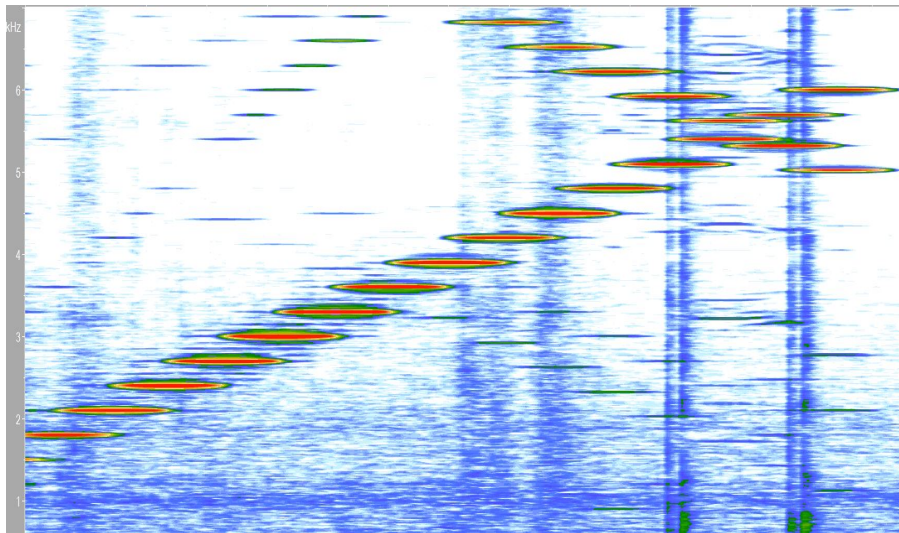


Figure: GaborAtoms02.jpg



# MATLupdown1

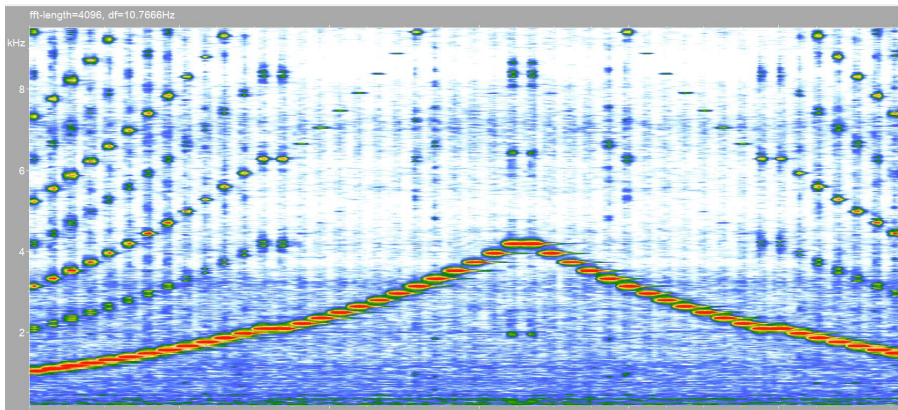


Figure: MATLupdown1.jpg



52	C5	c <sup>2</sup>	523,251
51	B4	h <sup>1</sup>	493,883
50	A#4/Bb4	ais <sup>1</sup> /b <sup>1</sup>	466,164
49	A4 [2]	a <sup>1</sup> Kammerton	440,000
48	G#4/Ab4	gis <sup>1</sup> /as <sup>1</sup>	415,305
47	G4	g <sup>1</sup>	391,995
46	F#4/Gb4	fis <sup>1</sup> /ges <sup>1</sup>	369,994
45	F4	f <sup>1</sup>	349,228
44	E4	e <sup>1</sup>	329,628
43	D#4/Eb4	dis <sup>1</sup> /es <sup>1</sup>	311,127
42	D4	d <sup>1</sup>	293,665
41	C#4/Db4	cis <sup>1</sup> /des <sup>1</sup>	277,183
40	C4[3]	c <sup>1</sup>	261,626

Figure: TonleiterCC1.jpg



# Cosine-Transforms: DCT, ICDT, DCT2, ICDT2

Sometimes the use of complex-valued building block from real-valued signals is not appreciated, and then one is calling for real variants of the Fourier transform. This can be obtained by using orthogonal matrices which are based on the cosine functions and form a (real) basis for real-valued signals. We will display some of the building blocks below.

Again we can reduce the two-dimensional version by iteration of the one-dimensional version. So if one has a fast code for the DCT/IDCT one has automatically a (well parallelizable) version for the  $2d$ -situation!



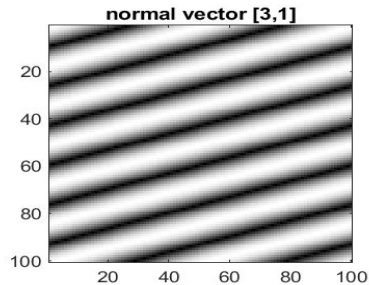
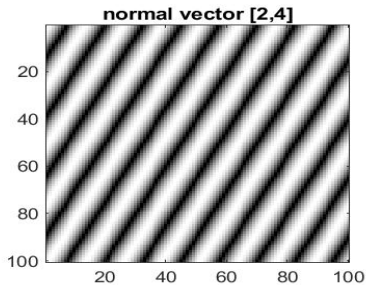
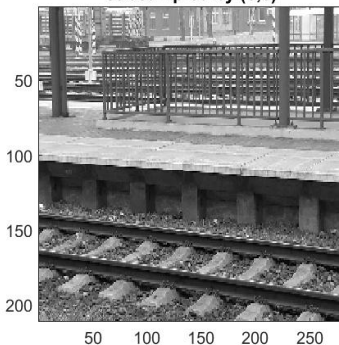


Figure: planewav2431.jpg

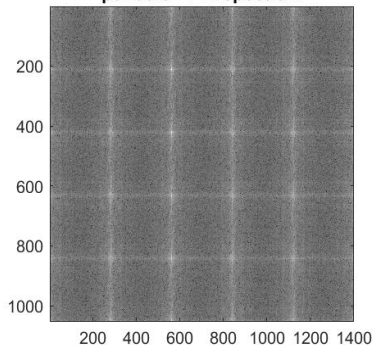


## subsamp55.jpg

subsamped by (5,5)



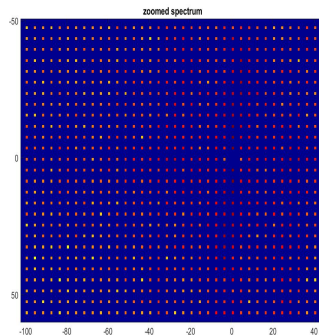
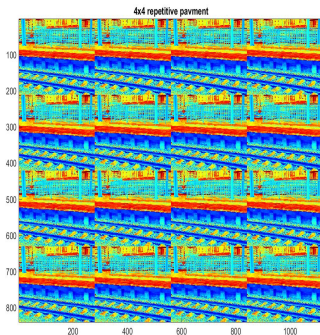
periodic FFT2 spectrum



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# repfourbfour4.jpg



## bsplindat03b.pdf

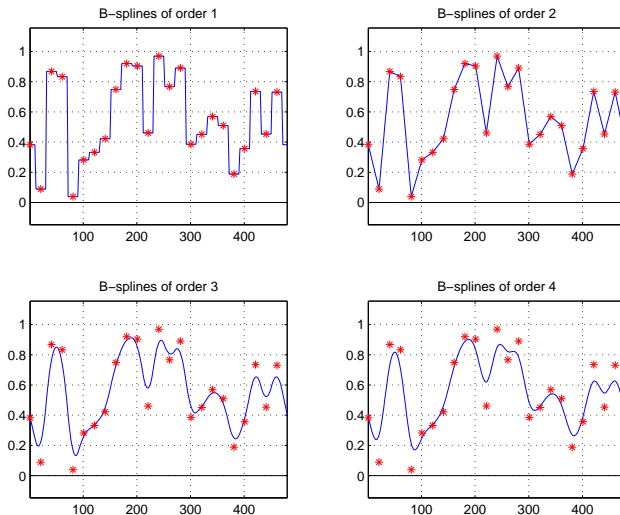


Figure: bsplindat03b.pdf

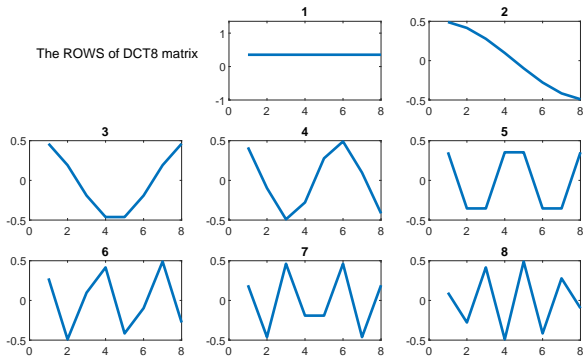


Figure: DC88demo2.eps



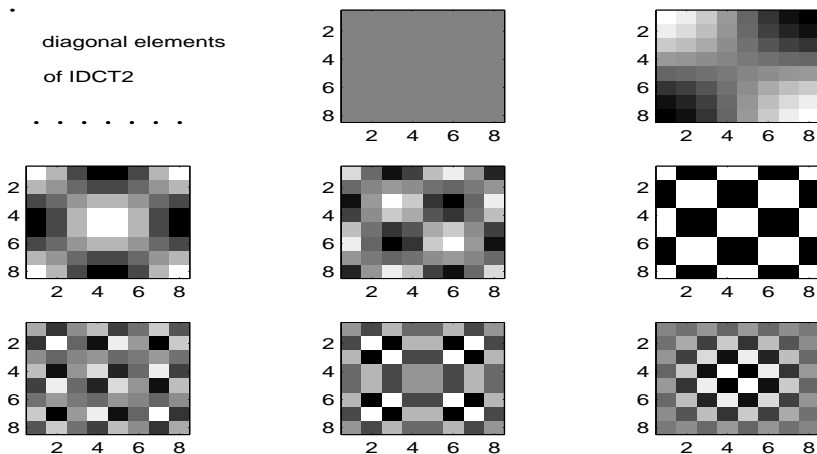


Figure: DCT88diag.pdf



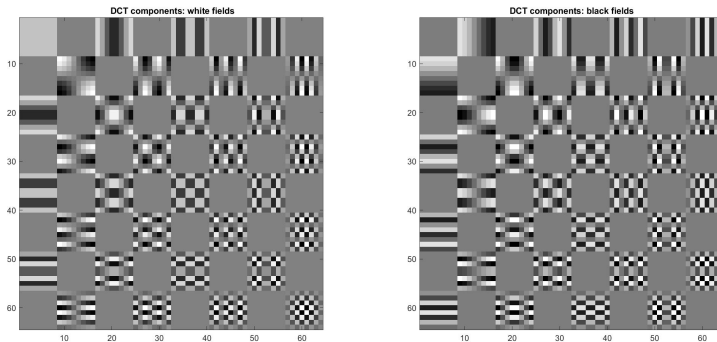


Figure: demoDCT202.jpg



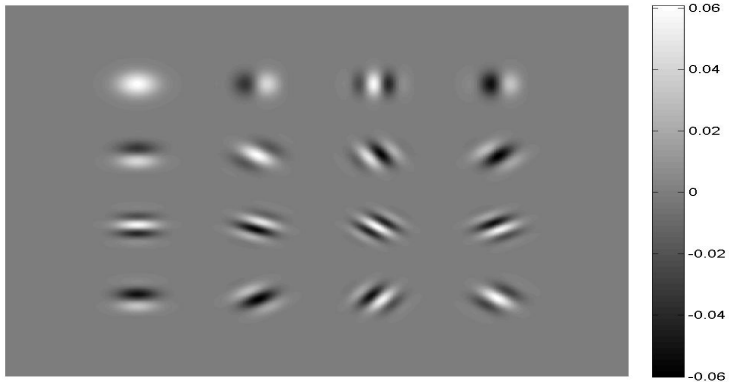


Figure: gabatom2b.jpg



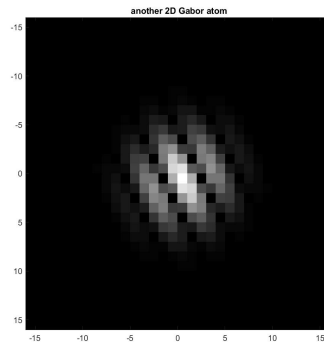
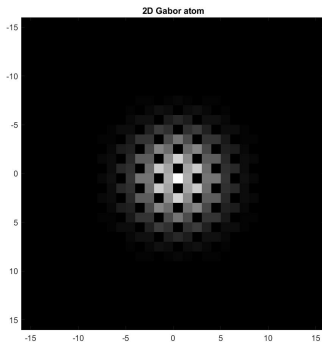


Figure: demogab202b.jpg



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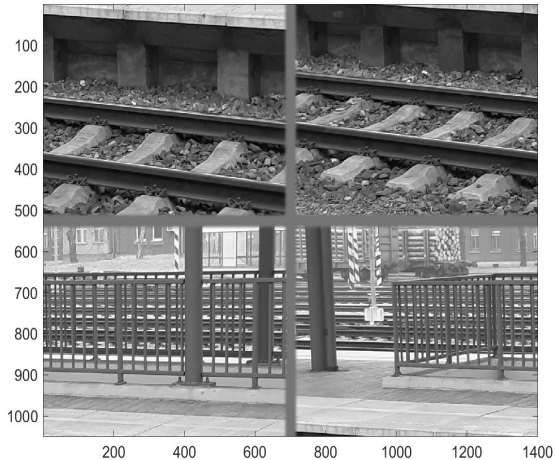


Figure: breclavsh1.jpg

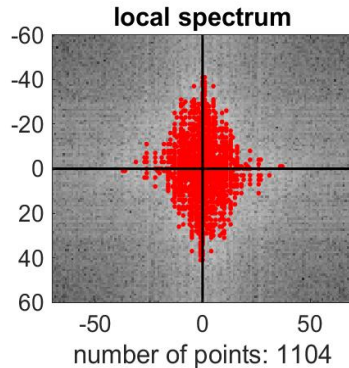
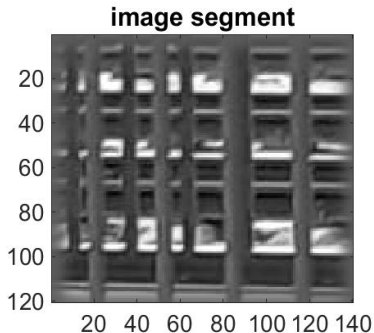


Figure: brecloc12.jpg





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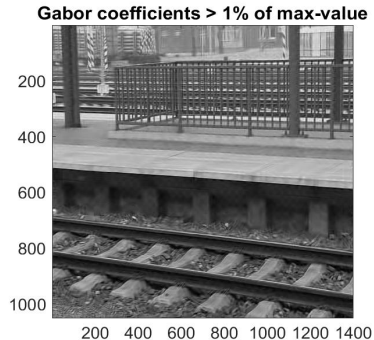
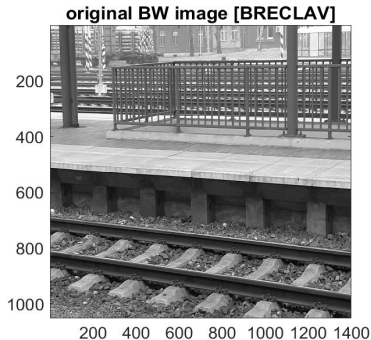
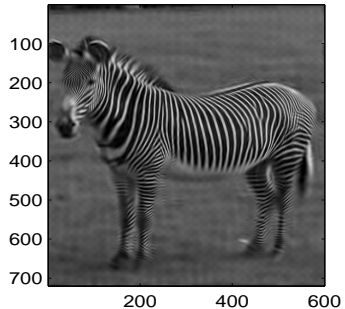
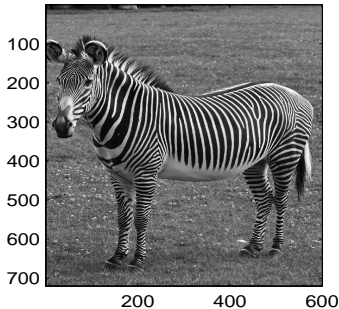


Figure: breclav002.jpg



# Image Compression



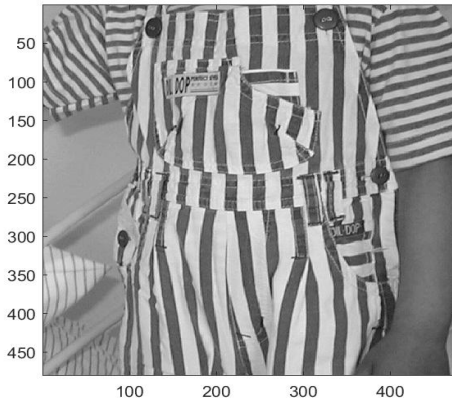


Figure: stripes480A.jpg: A test image, with stripes of different kind in different directions



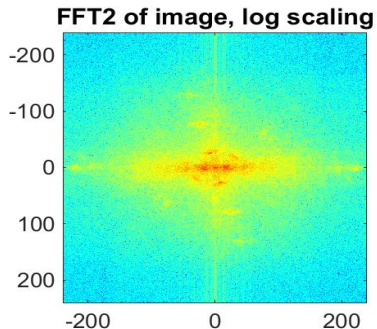
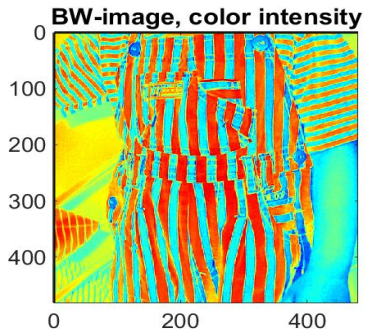
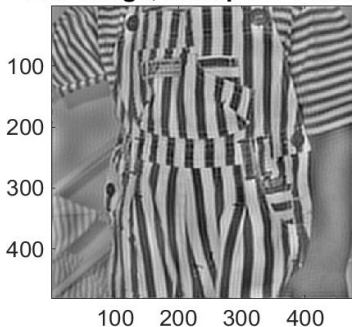


Figure: stripesFT2A.jpg



BW-image, bandpass version



FFT2 of image, log scaling

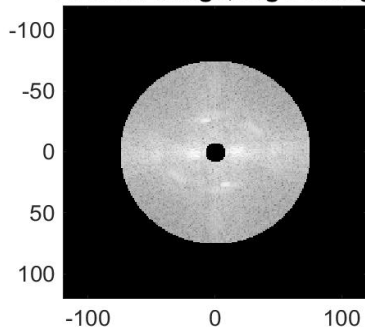


Figure: stripesFT2Ebw.jpg



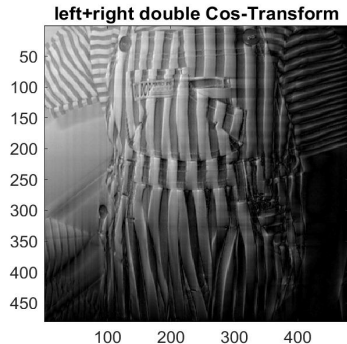
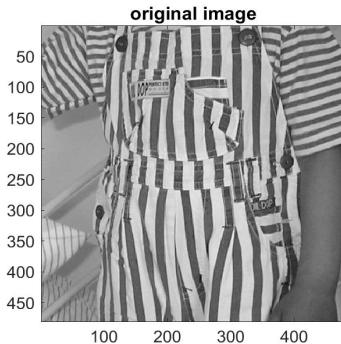


Figure: stripesFT2Fdoub.jpg



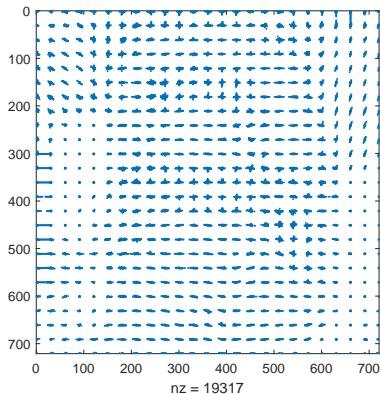
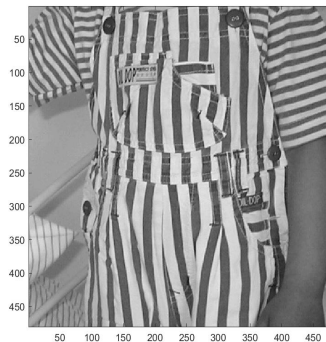
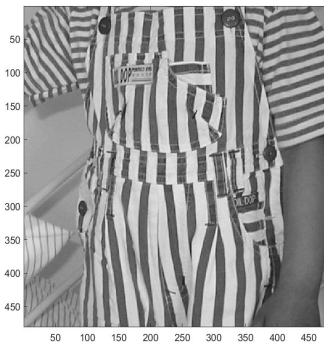


Figure: stripGab720a.eps



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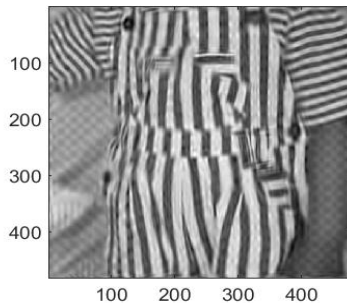
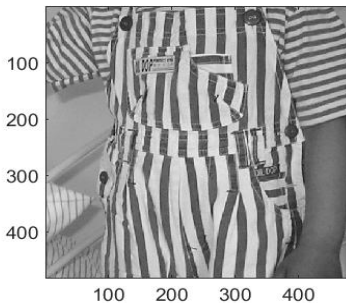


**Figure:** stripesFILTZA.jpg: ca. 3-4 percent of Gabor coefficients



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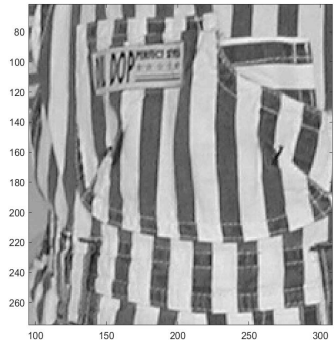
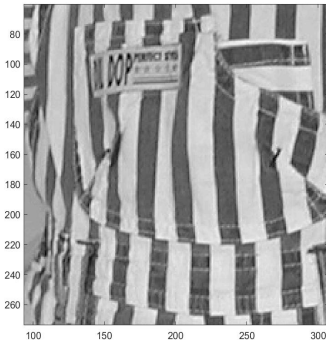


Figure: stripesFILTZ1.jpg





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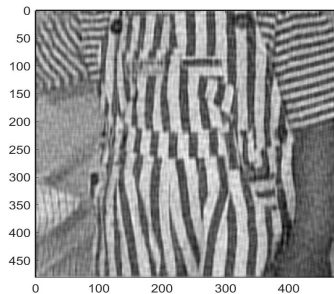
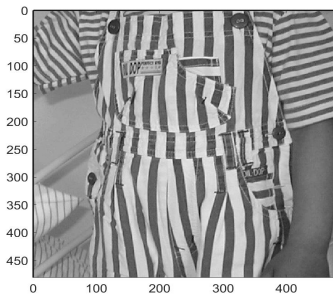
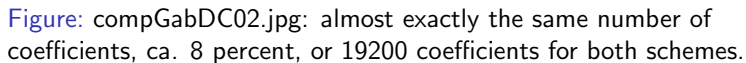


Figure: compGabDC01.jpg





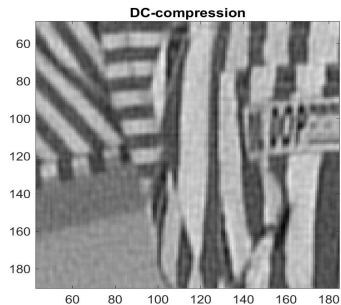
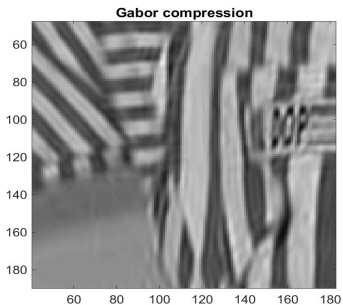


Figure: compGabDC02b.jpg



The work of H.L. Lebesgue paved the way to a clean definition of the Fourier transform for “functions of a continuous variables” as an *integral transform* naturally defined on  $(L^1(\mathbb{R}), \|\cdot\|_1)$

The (continuous) Fourier transform for  $f \in L^1(\mathbb{R})$  is given by:

With this normalization the inverse Fourier transform looks similar, just with the conjugate exponent, and thus, *under the assumption that  $f$  is continuous and  $\hat{f} \in L^1(\mathbb{R})$*  we have pointwise



# Plancherel's Theorem: Unitarity Property of FT

Using the density of  $L^1(\mathbb{R}) \cap L^2(\mathbb{R})$  in  $(L^2(\mathbb{R}), \|\cdot\|_2)$  it can be shown that the Fourier transform extends in a natural and unique way to  $(L^2(\mathbb{R}), \|\cdot\|_2)$ :

## Theorem

*The Fourier (-Plancherel) transform establishes a unitary automorphism of  $(L^2(\mathbb{R}), \|\cdot\|_2)$ , i.e. one has*

$$\|f\|_2 = \|\hat{f}\|_2, \quad f \in L^2(\mathbb{R}),$$

$$\langle f, g \rangle = \langle \hat{f}, \hat{g} \rangle, \quad f, g \in L^2(\mathbb{R}).$$

In some sense *unitary* transformations of a Hilbert transform is like a change from one ONB to another ONB in  $\mathbb{R}^n$ .



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# Function space norms

Function spaces are typically infinite-dimensional, therefore we are interested to allow convergent series. In order to check on them we need norms and completeness (in the metric sense), i.e. Banach spaces!

The classical function space norms are

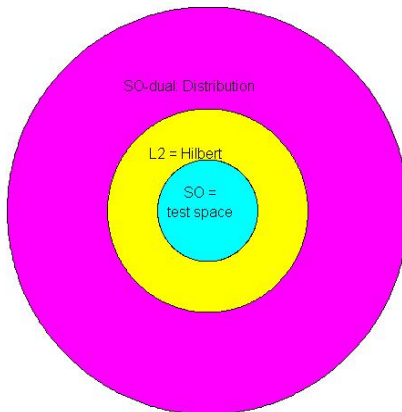
- $\|f\|_\infty := \sup_{t \in \mathbb{R}^d} |f(t)|;$
- $\|f\|_1 := \int_{\mathbb{R}^d} |f(x)| dx;$
- $\|f\|_2 := (\int_{\mathbb{R}^d} |f(x)|^2 dx)^{1/2};$
- $\|\mu\|_{\mathbf{M}_b(\mathbb{R}^d)} := \sup_{\|f\|_\infty \leq 1} |\mu(f)|$ , or  
 $\|\mu\|_{\mathbf{M}_b(\mathbb{R}^d)} = \int_{\mathbb{R}^d} 1 d|\mu|.$
- $\|h\|_{\mathcal{FL}^1} = \|f\|_1$ , for  $h = \hat{f}$ .



# A schematic description: the simplified setting

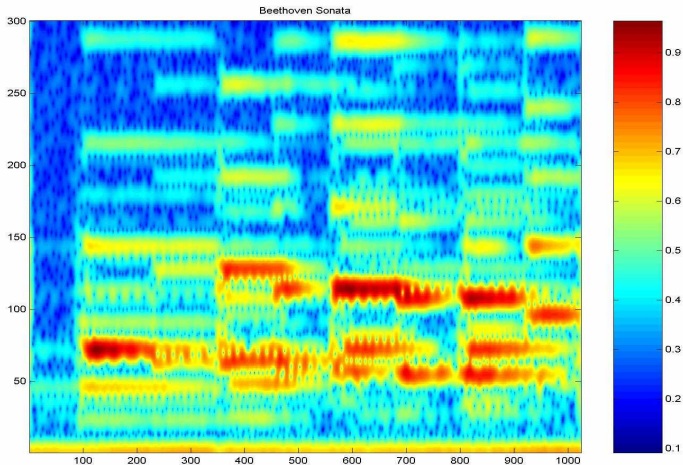
Testfunctions  $\subset$  Hilbert space  $\subset$  Distributions, like  $\mathbb{Q} \subset \mathbb{R} \subset \mathbb{C}$ !

the RIGGED Hilbert Space situation





# A Typical Musical STFT



## Demonstration using GEOGEBRA (very easy to use!!)



# Spectrogram versus Gabor Analysis

Assuming that we use as a “window” a Schwartz function  $g \in \mathcal{S}(\mathbb{R}^d)$ , or even the Gauss function  $g_0(t) = \exp(-\pi|t|^2)$ , we can define the spectrogram for general tempered distributions  $f \in \mathcal{S}'(\mathbb{R}^d)$ ! It is a continuous function over *phase space*.

In fact, for the case of the Gauss function it is *analytic* and in fact a member of the *Fock space*, of interest within complex analysis.

Both from a practical point of view and in view of this good smoothness one may expect that it is enough to *sample this spectrogram*, denoted by  $V_g(f)$  and still be able to reconstruct  $f$  (in analogy to the reconstruction of a band-limited signal from regular samples, according to Shannon's theorem).



So let us start from the continuous spectrogram

The spectrogram  $V_g(f)$ , with  $g, f \in L^2(\mathbb{R}^d)$  is well defined and has a number of good properties. Cauchy-Schwarz implies:

$$\|V_g(f)\|_\infty \leq \|f\|_2 \|g\|_2, \quad f, g \in L^2(\mathbb{R}^d),$$

in fact  $V_g(f) \in \mathbf{C}_0(\mathbb{R}^d \times \widehat{\mathbb{R}}^d)$ . Plancherel's Theorem gives

$$\|V_g(f)\|_2 = \|g\|_2 \|f\|_2, \quad g, f \in L^2(\mathbb{R}^d).$$

Assuming that  $g$  is normalized in  $L^2(\mathbb{R}^d)$ , or  $\|g\|_2 = 1$  makes  $f \mapsto V_g(f)$  isometric, hence we request this from now on. Note:  $V_g(f)$  is a complex-valued function, so we usually look at  $|V_g(f)|$ , or perhaps better  $|V_g(f)|^2$ , which can be viewed as a probability distribution over  $\mathbb{R}^d \times \widehat{\mathbb{R}}^d$  if  $\|f\|_2 = 1 = \|g\|_2$ .



## The continuous reconstruction formula

Now we can apply a simple abstract principle: Given an isometric embedding  $T$  of  $\mathcal{H}_1$  into  $\mathcal{H}_2$  the inverse (in the range) is given by the adjoint operator  $T^* : \mathcal{H}_2 \rightarrow \mathcal{H}_1$ , simply because  $\forall h \in \mathcal{H}_1$

$$\langle h, h \rangle_{\mathcal{H}_1} = \|h\|_{\mathcal{H}_1}^2 = (!) \|Th\|_{\mathcal{H}_2}^2 = \langle Th, Th \rangle_{\mathcal{H}_2} = \langle h, T^*Th \rangle_{\mathcal{H}_1}, \quad (9)$$

and thus by the *polarization principle*  $T^*T = Id$ .

In our setting we have (assuming  $\|g\|_2 = 1$ )  $\mathcal{H}_1 = \mathbf{L}^2(\mathbb{R}^d)$  and  $\mathcal{H}_2 = \mathbf{L}^2(\mathbb{R}^d \times \widehat{\mathbb{R}}^d)$ , and  $T = V_g$ . It is easy to check that

$$V_g^*(F) = \int_{\mathbb{R}^d \times \hat{\mathbb{R}}^d} F(\lambda) \pi(\lambda) g \, d\lambda, \quad F \in L^2(\mathbb{R}^d \times \hat{\mathbb{R}}^d), \quad (10)$$

understood in the weak sense, i.e. for  $h \in \mathbf{L}^2(\mathbb{R}^d)$  we expect:

$$\langle V_g^*(F), h \rangle_{L^2(\mathbb{R}^d)} = \int_{\mathbb{R}^d \times \widehat{\mathbb{R}}^d} F(x) \cdot \langle \pi(\lambda)g, h \rangle_{L^2(\mathbb{R}^d)} d\lambda. \quad (11)$$



## Continuous reconstruction formula II

Putting things together we have

$$\langle f, h \rangle = \langle V_g^*(V_g(f)), h \rangle = \int_{\mathbb{R}^d \times \widehat{\mathbb{R}}^d} V_g(f)(\lambda) \cdot \overline{V_g(h)(\lambda)} \, d\lambda. \quad (12)$$

A more suggestive presentation uses the symbol  $g_\lambda := \pi(\lambda)g$  and describes the inversion formula for  $\|g\|_2 = 1$  as:

$$f = \int_{\mathbb{R}^d \times \widehat{\mathbb{R}}^d} \langle f, g_\lambda \rangle g_\lambda d\lambda, \quad f \in L^2(\mathbb{R}^d). \quad (13)$$

This is quite analogous to the situation of the Fourier transform

$$f = \int_{\mathbb{R}^d} \langle f, \chi_s \rangle \chi_s ds, \quad f \in L^2(\mathbb{R}^d), \quad (14)$$

with  $\chi_s(t) = \exp(2\pi i \langle s, t \rangle)$ ,  $t, s \in \mathbb{R}^d$ , describing the “pure frequencies” (plane waves, resp. *characters* of  $\mathbb{R}^d$ ).



## A Banach Space of Test Functions (Fei 1979)

A function in  $f \in L^2(\mathbb{R}^d)$  is in the subspace  $\mathbf{S}_0(\mathbb{R}^d)$  if for some non-zero  $g$  (called the “window”) in the Schwartz space  $\mathcal{S}(\mathbb{R}^d)$

$$\|f\|_{S_0} := \|V_g f\|_{L^1} = \iint_{\mathbb{R}^d \times \widehat{\mathbb{R}}^d} |V_g f(x, \omega)| dx d\omega < \infty.$$

The space  $(\mathbf{S}_0(\mathbb{R}^d), \|\cdot\|_{\mathbf{s}_0})$  is a Banach space, for any fixed, non-zero  $g \in \mathbf{S}_0(\mathbb{R}^d)$ , and different windows  $g$  define the same space and equivalent norms. Since  $\mathbf{S}_0(\mathbb{R}^d)$  contains the Schwartz space  $\mathcal{S}(\mathbb{R}^d)$ , any Schwartz function is suitable, but also compactly supported functions having an integrable Fourier transform (such as a trapezoidal or triangular function) are suitable. It is convenient to use the Gaussian as a window.



## Basic properties of $M^1 = S_0(\mathbb{R}^d)$

## Lemma

Let  $f \in \mathbf{S}_0(\mathbb{R}^d)$ , then the following holds:

- (1)  $\pi(u, \eta)f \in \mathbf{S}_0(\mathbb{R}^d)$  for  $(u, \eta) \in \mathbb{R}^d \times \widehat{\mathbb{R}}^d$ , and  $\|\pi(u, \eta)f\|_{\mathbf{S}_0} = \|f\|_{\mathbf{S}_0}$ .
- (2)  $\hat{f} \in \mathbf{S}_0(\mathbb{R}^d)$ , and  $\|\hat{f}\|_{\mathbf{S}_0} = \|f\|_{\mathbf{S}_0}$ .

In fact,  $(\mathbf{S}_0(\mathbb{R}^d), \|\cdot\|_{\mathbf{S}_0})$  is the smallest non-trivial Banach space with this property, and therefore contained in any of the  $\mathbf{L}^p$ -spaces (and their Fourier images).







## The prototypical examples over the torus

In principle every CONB (= *complete orthonormal basis*)  $\Psi = (\psi_i)_{i \in I}$  for a given Hilbert space  $\mathcal{H}$  can be used to establish such a unitary isomorphism, by choosing as  $\mathbf{B}$  the space of elements within  $\mathcal{H}$  which have an absolutely convergent expansion, i.e. satisfy  $\sum_{i \in I} |\langle x, \psi_i \rangle| < \infty$ .

For the case of the Fourier system as CONB for  $\mathcal{H} = L^2([0, 1])$ , i.e. the corresponding definition is already around since the times of N. Wiener:  $\mathbf{A}(\mathbb{T})$ , the space of absolutely continuous Fourier series. It is also not surprising in retrospect to see that the dual space  $\mathbf{PM}(\mathbb{T}) = \mathbf{A}(\mathbb{T})'$  is space of *pseudo-measures*. One can extend the classical Fourier transform to this space, and in fact interpret this extended mapping, in conjunction with the classical Plancherel theorem as the first unitary Banach Gelfand triple isomorphism, between  $(\mathbf{A}, L^2, \mathbf{PM})(\mathbb{T})$  and  $(\ell^1, \ell^2, \ell^\infty)(\mathbb{Z})$ .



The **Fourier transform**  $\mathcal{F}$  on  $\mathbb{R}^d$  has the following properties:

- 1  $\mathcal{F}$  is an isomorphism from  $\mathbf{S}_0(\mathbb{R}^d)$  to  $\mathbf{S}_0(\widehat{\mathbb{R}}^d)$ ,
- 2  $\mathcal{F}$  is a unitary map between  $\mathbf{L}^2(\mathbb{R}^d)$  and  $\mathbf{L}^2(\widehat{\mathbb{R}}^d)$ ,
- 3  $\mathcal{F}$  is a weak\* (and norm-to-norm) continuous bijection from  $\mathbf{S}'_0(\mathbb{R}^d)$  onto  $\mathbf{S}'_0(\widehat{\mathbb{R}}^d)$ .

Furthermore, we have that Parseval's formula  $\langle f, g \rangle = \langle \widehat{f}, \widehat{g} \rangle$  for  $(f, g) \in \mathbf{S}_0(\mathbb{R}^d) \times \mathbf{S}'_0(\mathbb{R}^d)$ , and therefore on each level of the Gelfand triple  $(\mathbf{S}_0, L^2, \mathbf{S}'_0)(\mathbb{R}^d)$ .

Moreover  $\mathcal{F}$  is *uniquely determined* (as BGT $r$  isomorphism) by the property that  $\widehat{\chi_s} = \delta_s$ .



## A Banach Space of Test Functions (Fei 1979)

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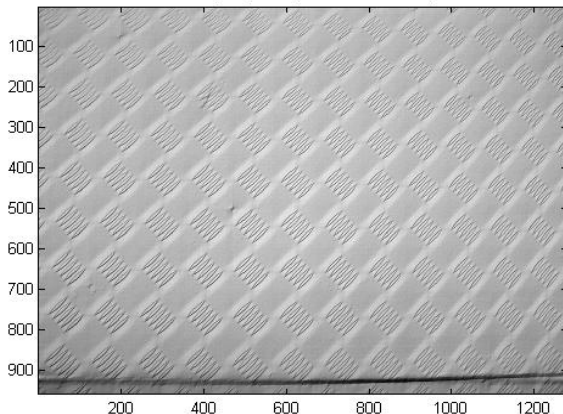


# The audio-engineer's work: Gabor multipliers

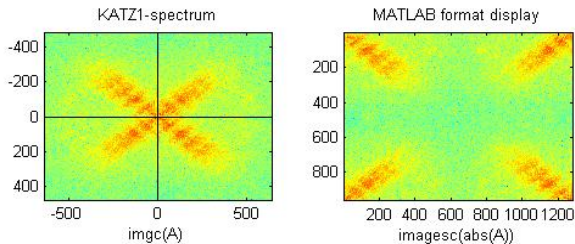


# 2D-Gabor Transform

reconstructing only one quadrant from the spectrum



## Ordinary FFT2 of test image



1. *Journal of Management Studies*, 1997, 34, 1, 1-14.

Now assume that we have a space-variant blurring function (or a *variable point-spread function*). But even if one has a perfect description it is not at all trivial to invert such an operator. As a first approximation one may view such an operator as Gabor multiplier with hopefully non-zero weights. Then one can hope that for regular weights one has good control of the difference between the inverse of such a Gabor multiplier and the Gabor multiplier with inverse symbol (bad and good audio engineer!).



# Frame and Riesz Basis

I do not want to give a formal definition of Frames or Riesz bases here, a good source is the book(s) of Ole Christensen.

One should think of **frames** as the correct generalization (to the setting of infinite dimensional Hilbert spaces) of the concept of *generating systems* (plus some stability). Each frame has a (canonical, and many non-canonical) dual frames.

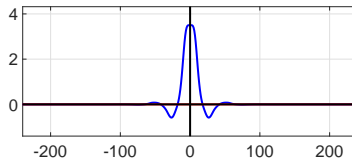
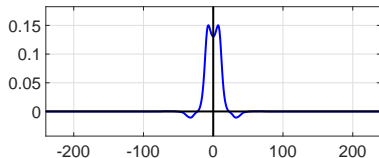
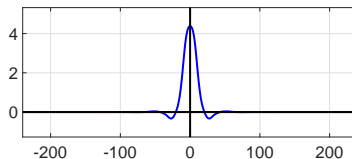
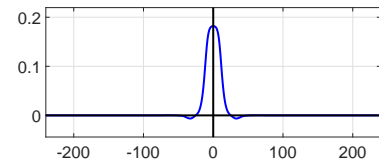
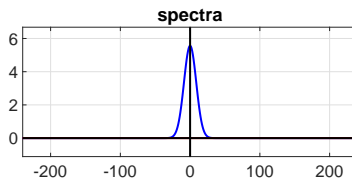
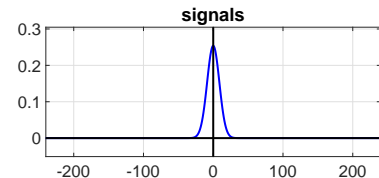
In Linear Algebra frames appear (under a different name) as matrices whose columns span the target space, i.e.  $\mathbb{C}^m$  or  $\mathbb{R}^m$ .

Since for each  $\mathbf{x} \in \mathbb{C}^m$  one has many representations one chooses the minimal norm representation. The (row-)vectors generating the corresponding coefficients are those which appear in the solution of the MNLSQ-problem (get those coefficients which have *minimal Euclidean norm*). This is closely related to the *Moore-Penrose inverse* of a (rectangular)  $\mathbf{A}$  of full rank, or in MATLAB notation  $\text{pinv}(\mathbf{A}') = \text{pinv}(\mathbf{A})'$ .





## Dual Gabor Atoms, Tight Gabor atoms



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- Wavelet theory and Gabor Analysis are *localized*, unlike the Fourier Analysis (pure frequencies last forever);
- Wavelet systems can be orthogonal AND *nice*, i.e. smooth and well decaying. The Balian-Low Theorem tell us that this is *impossible* in the Gabor case, so we have to live with *redundancy* and non-orthogonality;
- Still, regular Gabor Analysis, in particular tight Gabor families (which work almost like ONBs) can be constructed in a numerically efficient way.



# Some Challenges in Time-Frequency Analysis

Whereas the *regular Gabor Analysis* is well established, and we know how to find e.g. the best approximation (in the Frobenius norm, i.e. with respect to the Euclidean structure if  $\mathbb{C}^{n^2}$ ) of a given matrix by a Gabor multiplier the question of describing *optimality*, we see still an extensive collection of open question, also with respect to numerically efficient realization of theoretical ideas.

Recent work of *Markus Faulhuber* indicates that at least for (generalized) Gaussian windows this is related to (sphere) packing problems, based on invariance properties (using symplectic and metaplectic groups), see [1],[3], and [2]. For 1D-signals and ordinary (Fourier invariant) Gaussians appear to be optimal.





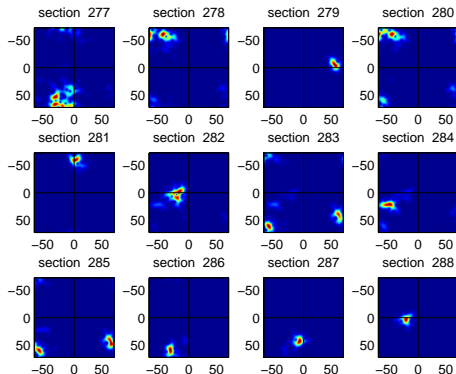


Figure: gabirrlast1.pdf

This picture shows that the dual frame for an irregular Gabor





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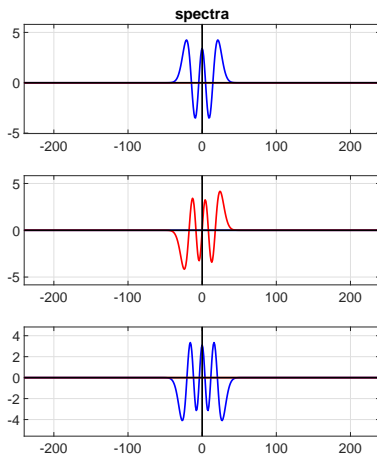
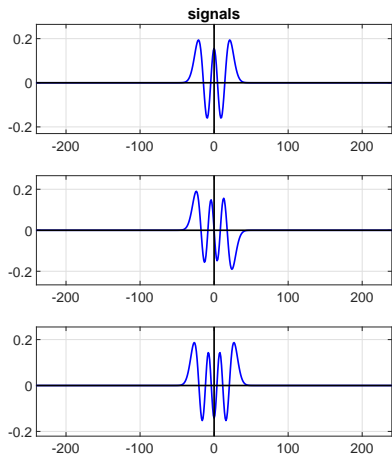
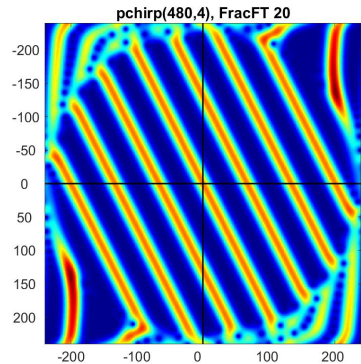


Figure: herm5to7A.eps





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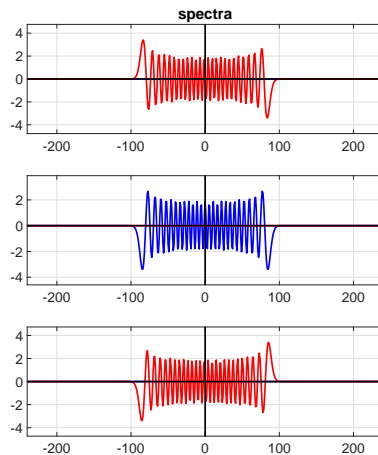
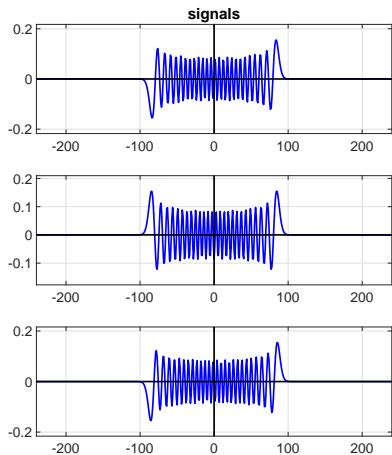


Figure: herm50to52.eps





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# Encore: last slides of Jarnik Lecture









# Gravitational waves and Wilson bases

There is not enough time to explain the details of the huge signal processing task behind these findings, the literal “needle in the haystack”.

There had been two strategies:

- Searching for 2500 explicitly determined wave-forms;
- Using a family of 14 orthonormal Wilson bases in order to detect the gravitational waves.

The very **first** was detected by the second strategy, because the masses had been out of the expected range of the predetermined wave-forms.

NOTE: Wilson bases are cooked up from tight Gabor frames of redundancy 2 by pairing them, like  $\cos(x)$  and  $\sin(x)$  using Euler's formula (in a smart, woven way).



# THANK YOU

## Thank you for your attention

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In particular [www.nuhag.eu/talks](http://www.nuhag.eu/talks)

